

# Fast learning of fast transforms, with guarantees

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## Approximating a matrix by a product of sparse factors

Given a matrix  $\mathbf{Z}$  and  $J \geq 2$ , find **sparse** factors  $\mathbf{X}^{(J)}, \dots, \mathbf{X}^{(1)}$  such that

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Reduce time/memory complexity: find  $\mathbf{x}$  such that  $\mathbf{y} = \mathbf{Z}\mathbf{x}$ .

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### Application (Deep neural network compression)

Replace a dense **weight** matrix  $\mathbf{Z}$  by  $\mathbf{X}^{(J)} \dots \mathbf{X}^{(1)}$ .

**Figure:** Variants of Vision Transformers [Dosovitskiy et al, 2021]

Model	Layers	Hidden size $D$	MLP size	Heads	Params
ViT-Base	12	768	3072	12	86M
ViT-Large	24	1024	4096	16	307M
ViT-Huge	32	1280	5120	16	632M

# Approximating a matrix by a product of sparse factors

## Problem formulation

$$\min_{\mathbf{X}^{(1)}, \dots, \mathbf{X}^{(J)}} \left\| \mathbf{Z} - \mathbf{X}^{(J)} \mathbf{X}^{(J-1)} \dots \mathbf{X}^{(1)} \right\|_F^2, \quad \text{such that } \{\mathbf{X}^{(\ell)}\}_\ell \text{ are sparse.} \quad (1)$$

Choices for sparsity constraint:

- 1 **Classical sparsity patterns:**  $k$ -sparsity by column and/or by row
- 2 **Fixed-support constraint:**  $\text{supp}(\mathbf{X}^{(\ell)}) \subseteq \mathbf{S}^{(\ell)}$  for  $\ell = 1, \dots, J$ .

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## A difficult problem

- Sparse coding is NP-hard [Foucart et al. 2013].
- Fixed-support setting is NP-hard for  $J = 2$  factors [Le et al. 2021].
- Gradient-based methods [Le Magoarou et al. 2016] lack guarantees.

## Focus on fixed-support constraint

When is the problem well-posed and tractable? (case with  $J = 2$ )

- 1 Conditions for uniqueness of the solution [Zheng et al. 2022]
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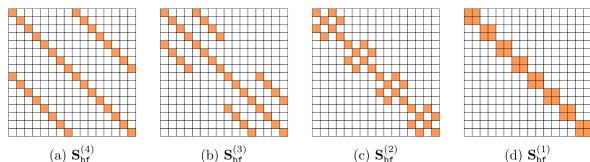


Figure: Butterfly structure:  $\text{supp}(\mathbf{X}^{(\ell)}) \subseteq \mathbf{S}_{br}^{(\ell)} := \mathbf{I}_{N/2^\ell} \otimes \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix} \otimes \mathbf{I}_{2^{\ell-1}}$ .

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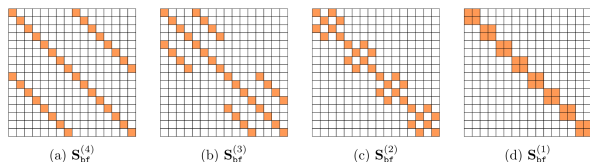


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Why **butterfly** structure?

- Allows fast  $\mathcal{O}(N \log N)$  matrix-vector multiplication
- Captures DFT, DCT, Hadamard, convolution, ... [Dao et al. 2020]

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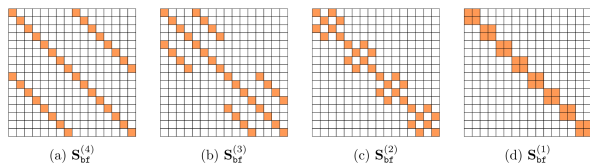


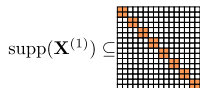
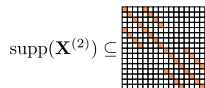
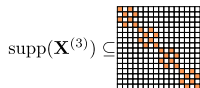
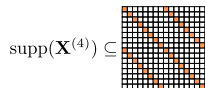
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## Main contribution

An efficient **hierarchical algorithm** to approximate **any** matrix by a product of **butterfly** factors.

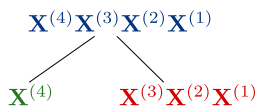
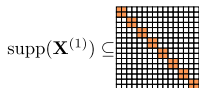
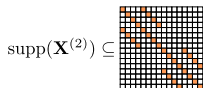
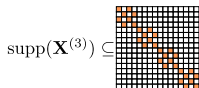
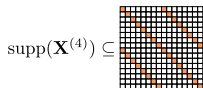
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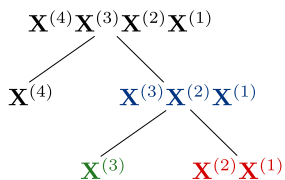
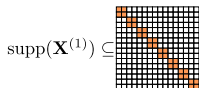
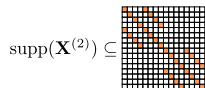
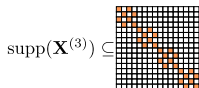
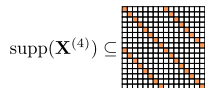
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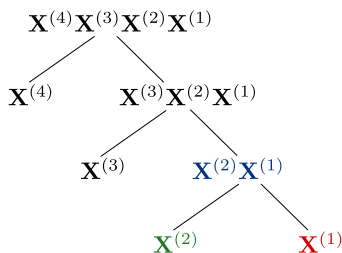
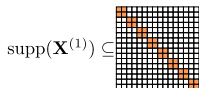
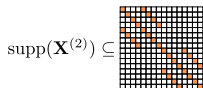
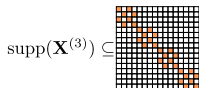
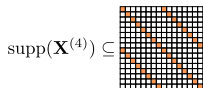
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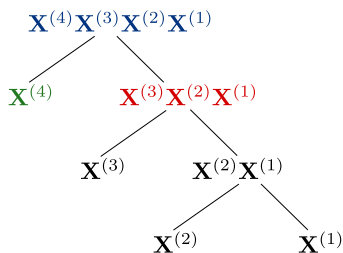
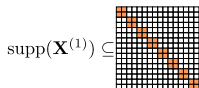
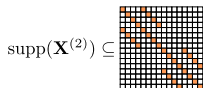
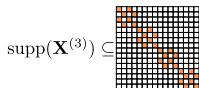
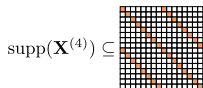
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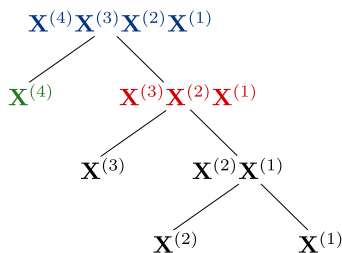
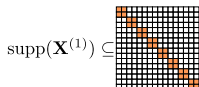
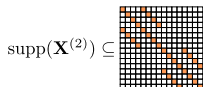
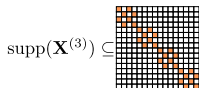
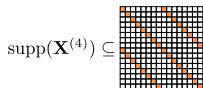


How to recover the partial products?




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
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How to recover the partial products?  $\rightarrow$  use their known supports

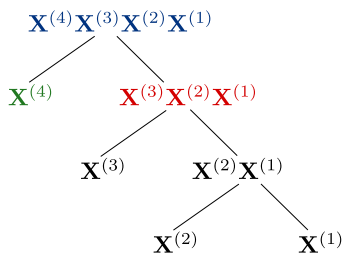
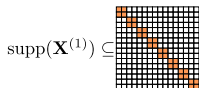
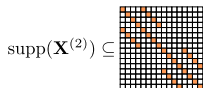
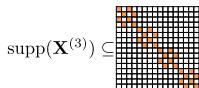
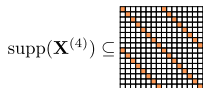
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$$\text{supp}(\mathbf{X}^{(4)}) \subseteq \text{} = \mathbf{S}_{\text{bf}}^{(4)}$$

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
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
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Two-layer fixed-support problem:

$$\min_{\mathbf{A}, \mathbf{B}} \|\mathbf{Z} - \mathbf{A}\mathbf{B}\|_F^2, \text{ s.t. } \text{supp}(\mathbf{A}) \subseteq \mathbf{S}_{\text{bf}}^{(4)}, \text{supp}(\mathbf{B}) \subseteq \mathbf{S}_{\text{bf}}^{(3)}\mathbf{S}_{\text{bf}}^{(2)}\mathbf{S}_{\text{bf}}^{(1)} \quad (2)$$

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Constraint on the pair of factors

$$\text{supp}(\mathbf{A}) \subseteq \begin{array}{c} \text{[Grid with green diagonal pattern]} \\ = \mathbf{S}_{\text{bf}}^{(4)} \end{array}$$

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⋮

$$\text{supp}(\mathbf{A}_{\bullet,N}\mathbf{B}_{N,\bullet}) \subseteq \begin{array}{c} \text{[Grid with purple horizontal line]} \\ = \mathcal{S}_N \end{array}$$

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Theorem ([Le et al. 2021; Zheng et al. 2022])

The rank-one matrices have **pairwise disjoint supports**. Consequently, (1) is **polynomially solvable** and admits an essentially **unique** solution.

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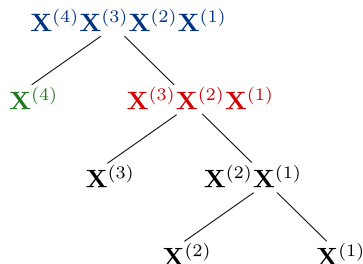
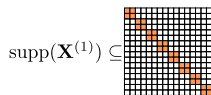
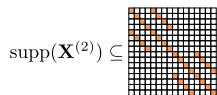
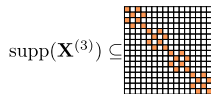
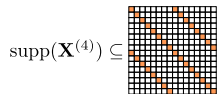
**Algorithm** to solve (1):

- 1 Extract the submatrices  $\mathbf{Z}_{|\mathcal{S}_i}$ ,  $i = 1, \dots, N$
- 2 Perform best rank-one approximation for each submatrix




# Hierarchical factorization algorithm


Let  $\mathbf{Z} := \mathbf{X}^{(4)}\mathbf{X}^{(3)}\mathbf{X}^{(2)}\mathbf{X}^{(1)}$  such that:



The two-layer procedure is repeated **recursively**.

## Lemma (Support of the partial products)

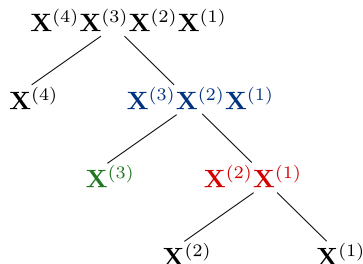
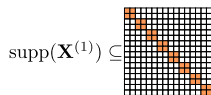
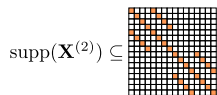
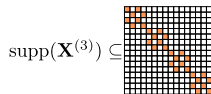
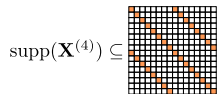
$$\text{supp}(\mathbf{X}^{(4)}) \subseteq \text{} = \mathbf{S}_{\text{bf}}^{(4)}$$

$$\text{supp}(\mathbf{X}^{(3)}\mathbf{X}^{(2)}\mathbf{X}^{(1)}) \subseteq \text{} = \mathbf{S}_{\text{bf}}^{(3)}\mathbf{S}_{\text{bf}}^{(2)}\mathbf{S}_{\text{bf}}^{(1)}$$

*The corresponding rank-one supports are pairwise disjoint.*

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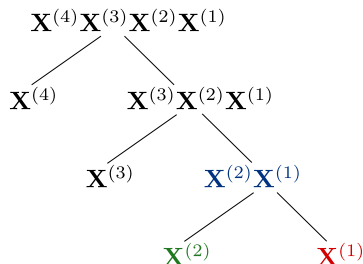
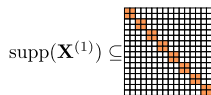
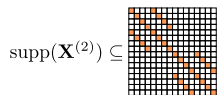
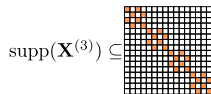
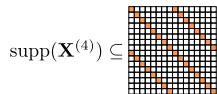
$$\text{supp}(\mathbf{X}^{(3)}) \subseteq \text{img} \quad = \mathbf{S}_{\text{bf}}^{(3)}$$

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
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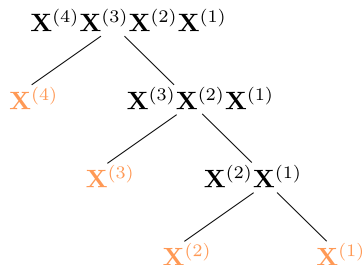
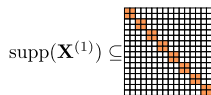
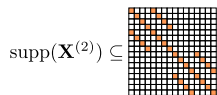
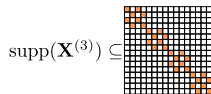
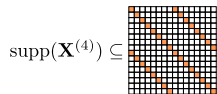
$\text{supp}(\mathbf{X}^{(2)}) \subseteq$    $= \mathbf{S}_{\text{bf}}^{(2)}$

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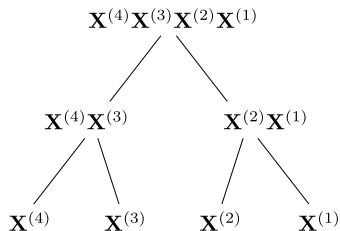
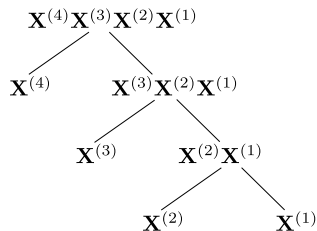
$$\text{supp}(\mathbf{X}^{(1)}) \subseteq \text{img} = \mathbf{S}_{\text{bf}}^{(1)}$$

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The butterfly factors  $\{\mathbf{X}^{(\ell)}\}_{\ell=1}^4$  are recovered (up to scaling ambiguities) from the product  $\mathbf{Z}$ .

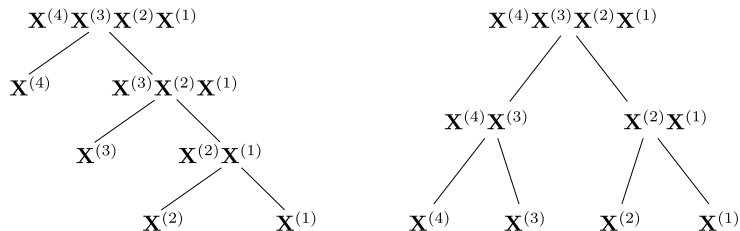
# Theoretical guarantees

The algorithm works for **any number of factors** and **any binary tree**.



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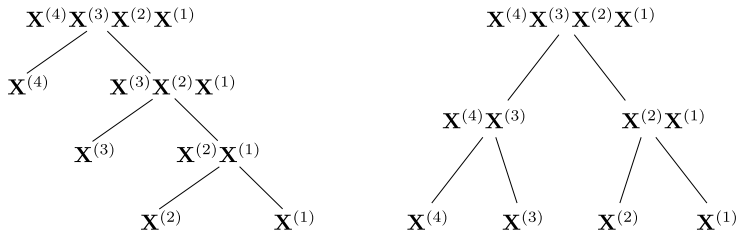


**Theorem (Exact recovery guarantees [Zheng et al. 2022])**

*Except for trivial degeneracies, every tuple  $(\mathbf{X}^{(\ell)})_{\ell=1}^J$  satisfying the butterfly constraint can be reconstructed by the algorithm from  $\mathbf{Z} := \mathbf{X}^{(J)} \dots \mathbf{X}^{(1)}$  (up to unavoidable scaling ambiguities).*

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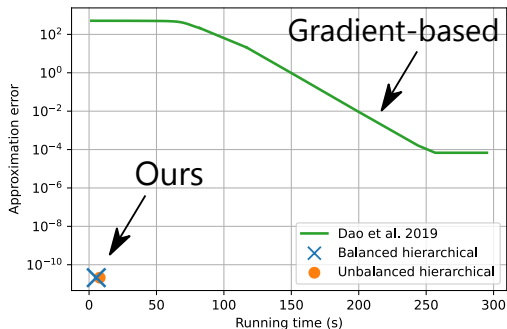
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- Complexity is  $\mathcal{O}(N^2)$  for both trees.
- We can use the algorithm in the non-exact setting.

# Faster and more accurate in the **noiseless setting**

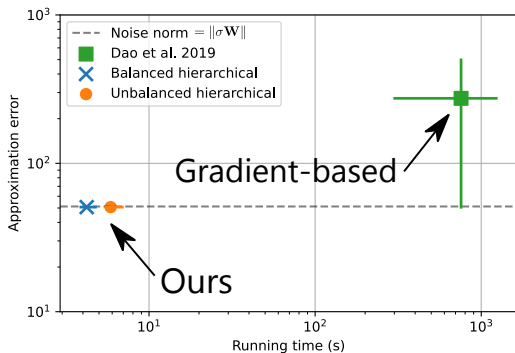
Approximation of the DFT matrix by a product of  $J = 9$  butterfly factors:





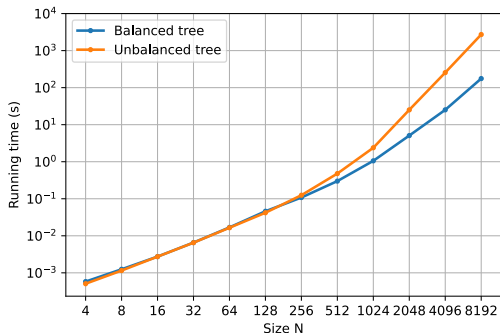
## Also more robust in the **noisy setting**

Approximation of  $\mathbf{Z} = \mathbf{DFT}_N + \sigma\mathbf{W}$  by a product of  $J = 9$  butterfly factors:



## Our method **scales** with the matrix size

Approximation of the (noisy) DFT matrix of size  $N = 2^J$  by a product of  $J$  butterfly factors:



## Conclusion and perspectives

Hierarchical algorithm:  $\mathcal{O}(N^2)$



$$\mathbf{Z} \in \mathbb{R}^{N \times N} \text{ (dense)}$$

Storage:  $\mathcal{O}(N^2)$

Cost for evaluation:  $\mathcal{O}(N^2)$

$$\mathbf{x} \mapsto \mathbf{Z}\mathbf{x}$$

$$\tilde{\mathbf{Z}} := \mathbf{X}^{(J)} \mathbf{X}^{(J-1)} \dots \mathbf{X}^{(1)}$$

Storage:  $\mathcal{O}(N \log N)$

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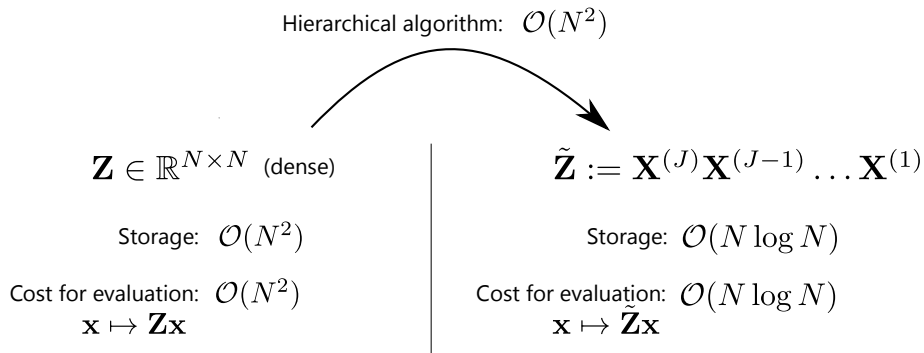
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Implementation in the FA $\mu$ ST toolbox at <https://faust.inria.fr>.

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## Future work

- Application in dictionary learning, sparse neural network training, ...
- Stability properties of the hierarchical algorithm

# Thank you for your attention!

To know more:



Q.-T. Le, L. Zheng, E. Riccietti, and R. Gribonval (2022)

Fast learning of fast transforms, with guarantees  
[In ICASSP, 2022.](#)



Q.-T. Le, E. Riccietti, and R. Gribonval (2022)

Spurious Valleys, Spurious Minima and NP-hardness of Sparse Matrix Factorization With Fixed Support  
[arXiv preprint, arXiv:2112.00386.](#)



L. Zheng, E. Riccietti, and R. Gribonval (2022)

Efficient Identification of Butterfly Sparse Matrix Factorizations  
[arXiv preprint, arXiv:2110.01235.](#)