

Efficient Identification of Butterfly Sparse Matrix Factorizations

Léon Zheng, Elisa Riccietti, Rémi Gribonval

March 2 - SIAM CSE 2023

valeo.ai



Inria

Sparse matrix factorization

Given a matrix \mathbf{Z} and $J \geq 2$, find **sparse** factors $\mathbf{X}^{(1)}, \dots, \mathbf{X}^{(J)}$ such that

$$\mathbf{Z} \approx \mathbf{X}^{(1)}\mathbf{X}^{(2)} \dots \mathbf{X}^{(J)}.$$

Sparse matrix factorization

Given a matrix \mathbf{Z} and $J \geq 2$, find **sparse** factors $\mathbf{X}^{(1)}, \dots, \mathbf{X}^{(J)}$ such that

$$\mathbf{Z} \approx \mathbf{X}^{(1)}\mathbf{X}^{(2)} \dots \mathbf{X}^{(J)}.$$

Fast matrix-vector multiplication: $\mathbf{Z}\mathbf{x} \approx \mathbf{X}^{(1)}\mathbf{X}^{(2)} \dots \mathbf{X}^{(J)}\mathbf{x}$.

Sparse matrix factorization

Given a matrix \mathbf{Z} and $J \geq 2$, find **sparse** factors $\mathbf{X}^{(1)}, \dots, \mathbf{X}^{(J)}$ such that

$$\mathbf{Z} \approx \mathbf{X}^{(1)}\mathbf{X}^{(2)} \dots \mathbf{X}^{(J)}.$$

Fast matrix-vector multiplication: $\mathbf{Z}\mathbf{x} \approx \mathbf{X}^{(1)}\mathbf{X}^{(2)} \dots \mathbf{X}^{(J)}\mathbf{x}$.

Example (Fourier integral operators)

Fast evaluation of $u(x) = \sum_{k \in \Omega} e^{2\pi i \Phi(x,k)} f(k)$, for all $x \in X$?

Sparse matrix factorization

Given a matrix \mathbf{Z} and $J \geq 2$, find **sparse** factors $\mathbf{X}^{(1)}, \dots, \mathbf{X}^{(J)}$ such that

$$\mathbf{Z} \approx \mathbf{X}^{(1)}\mathbf{X}^{(2)} \dots \mathbf{X}^{(J)}.$$

Fast matrix-vector multiplication: $\mathbf{Z}\mathbf{x} \approx \mathbf{X}^{(1)}\mathbf{X}^{(2)} \dots \mathbf{X}^{(J)}\mathbf{x}$.

Example (Fourier integral operators)

Fast evaluation of $u(x) = \sum_{k \in \Omega} e^{2\pi i \Phi(x,k)} f(k)$, for all $x \in X$?

Factorize $\mathbf{K} := (e^{2\pi i \Phi(x,k)})_{x \in X, k \in \Omega} \approx \mathbf{X}^{(1)} \dots \mathbf{X}^{(J)}$.

[E. Candes et al., A fast butterfly algorithm for the computation of Fourier integral operators, MMS, 2009]

Sparse matrix factorization

Given a matrix \mathbf{Z} and $J \geq 2$, find **sparse** factors $\mathbf{X}^{(1)}, \dots, \mathbf{X}^{(J)}$ such that

$$\mathbf{Z} \approx \mathbf{X}^{(1)} \mathbf{X}^{(2)} \dots \mathbf{X}^{(J)}.$$

Fast matrix-vector multiplication: $\mathbf{Z}\mathbf{x} \approx \mathbf{X}^{(1)} \mathbf{X}^{(2)} \dots \mathbf{X}^{(J)} \mathbf{x}$.

Example (Fourier integral operators)

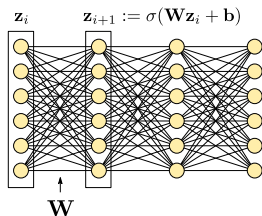
Fast evaluation of $u(x) = \sum_{k \in \Omega} e^{2\pi i \Phi(x,k)} f(k)$, for all $x \in X$?

Factorize $\mathbf{K} := (e^{2\pi i \Phi(x,k)})_{x \in X, k \in \Omega} \approx \mathbf{X}^{(1)} \dots \mathbf{X}^{(J)}$.

[E. Candes et al., **A fast butterfly algorithm for the computation of Fourier integral operators**, MMS, 2009]

Example (Compress neural network)

Factorize weight matrices in overparameterized neural networks.



[T. Dao et al., **Monarch: Expressive structured matrices for efficient and accurate training**, ICML, 2022]

Sparse matrix factorization

Given a matrix \mathbf{Z} and $J \geq 2$, find **sparse** factors $\mathbf{X}^{(1)}, \dots, \mathbf{X}^{(J)}$ such that

$$\mathbf{Z} \approx \mathbf{X}^{(1)}\mathbf{X}^{(2)} \dots \mathbf{X}^{(J)}.$$

Fast matrix-vector multiplication: $\mathbf{Z}\mathbf{x} \approx \mathbf{X}^{(1)}\mathbf{X}^{(2)} \dots \mathbf{X}^{(J)}\mathbf{x}$.

Example (Fourier integral operators)

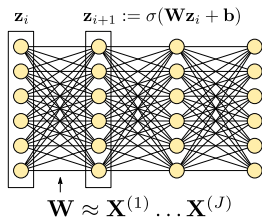
Fast evaluation of $u(x) = \sum_{k \in \Omega} e^{2\pi i \Phi(x,k)} f(k)$, for all $x \in X$?

Factorize $\mathbf{K} := (e^{2\pi i \Phi(x,k)})_{x \in X, k \in \Omega} \approx \mathbf{X}^{(1)} \dots \mathbf{X}^{(J)}$.

[E. Candes et al., **A fast butterfly algorithm for the computation of Fourier integral operators**, MMS, 2009]

Example (Compress neural network)

Factorize weight matrices in overparameterized neural networks.



[T. Dao et al., **Monarch: Expressive structured matrices for efficient and accurate training**, ICML, 2022]

How to factorize a matrix into sparse factors?

Problem formulation

$$\min_{\mathbf{x}^{(1)}, \dots, \mathbf{x}^{(J)}} \left\| \mathbf{Z} - \mathbf{x}^{(1)} \mathbf{x}^{(2)} \dots \mathbf{x}^{(J)} \right\|_F, \quad \text{such that } \{\mathbf{x}^{(\ell)}\}_\ell \text{ are sparse.}$$

Choices for sparsity constraint?

How to factorize a matrix into sparse factors?

Problem formulation

$$\min_{\mathbf{x}^{(1)}, \dots, \mathbf{x}^{(J)}} \left\| \mathbf{Z} - \mathbf{x}^{(1)} \mathbf{x}^{(2)} \dots \mathbf{x}^{(J)} \right\|_F, \quad \text{such that } \{\mathbf{x}^{(\ell)}\}_\ell \text{ are sparse.}$$

Choices for sparsity constraint?

- 1 **Classical sparsity patterns:** k -sparsity by column and/or by row

How to factorize a matrix into sparse factors?

Problem formulation

$$\min_{\mathbf{x}^{(1)}, \dots, \mathbf{x}^{(J)}} \left\| \mathbf{Z} - \mathbf{x}^{(1)} \mathbf{x}^{(2)} \dots \mathbf{x}^{(J)} \right\|_F, \quad \text{such that } \{\mathbf{x}^{(\ell)}\}_\ell \text{ are sparse.}$$

Choices for sparsity constraint?

- 1 **Classical sparsity patterns:** k -sparsity by column and/or by row
- 2 **Fixed-support constraint:** $\text{supp}(\mathbf{x}^{(\ell)}) \subseteq \mathbf{S}^{(\ell)}$ for $\ell = 1, \dots, J$.

How to factorize a matrix into sparse factors?

Problem formulation

$$\min_{\mathbf{X}^{(1)}, \dots, \mathbf{X}^{(J)}} \left\| \mathbf{Z} - \mathbf{X}^{(1)} \mathbf{X}^{(2)} \dots \mathbf{X}^{(J)} \right\|_F, \quad \text{such that } \{\mathbf{X}^{(\ell)}\}_\ell \text{ are sparse.}$$

Choices for sparsity constraint?

- 1 **Classical sparsity patterns:** k -sparsity by column and/or by row
- 2 **Fixed-support constraint:** $\text{supp}(\mathbf{X}^{(\ell)}) \subseteq \mathbf{S}^{(\ell)}$ for $\ell = 1, \dots, J$.

A difficult problem

How to factorize a matrix into sparse factors?

Problem formulation

$$\min_{\mathbf{X}^{(1)}, \dots, \mathbf{X}^{(J)}} \left\| \mathbf{Z} - \mathbf{X}^{(1)} \mathbf{X}^{(2)} \dots \mathbf{X}^{(J)} \right\|_F, \quad \text{such that } \{\mathbf{X}^{(\ell)}\}_\ell \text{ are sparse.}$$

Choices for sparsity constraint?

- 1 **Classical sparsity patterns:** k -sparsity by column and/or by row
- 2 **Fixed-support constraint:** $\text{supp}(\mathbf{X}^{(\ell)}) \subseteq \mathbf{S}^{(\ell)}$ for $\ell = 1, \dots, J$.

A difficult problem

- Sparse coding is NP-hard.

[S. Foucart, H. Rauhut, **A mathematical introduction to compressive sensing**, ANHA, 2013]

How to factorize a matrix into sparse factors?

Problem formulation

$$\min_{\mathbf{X}^{(1)}, \dots, \mathbf{X}^{(J)}} \left\| \mathbf{Z} - \mathbf{X}^{(1)} \mathbf{X}^{(2)} \dots \mathbf{X}^{(J)} \right\|_F, \quad \text{such that } \{\mathbf{X}^{(\ell)}\}_\ell \text{ are sparse.}$$

Choices for sparsity constraint?

- 1 **Classical sparsity patterns:** k -sparsity by column and/or by row
- 2 **Fixed-support constraint:** $\text{supp}(\mathbf{X}^{(\ell)}) \subseteq \mathbf{S}^{(\ell)}$ for $\ell = 1, \dots, J$.

A difficult problem

- Sparse coding is NP-hard.

[S. Foucart, H. Rauhut, **A mathematical introduction to compressive sensing**, ANHA, 2013]

- Fixed-support setting is NP-hard for $J = 2$ factors.

[Le et al., **Spurious valleys, NP-hardness, and tractability of sparse matrix fact. with fixed support**, SIMAX, 2022]

How to factorize a matrix into sparse factors?

Problem formulation

$$\min_{\mathbf{X}^{(1)}, \dots, \mathbf{X}^{(J)}} \left\| \mathbf{Z} - \mathbf{X}^{(1)} \mathbf{X}^{(2)} \dots \mathbf{X}^{(J)} \right\|_F, \quad \text{such that } \{\mathbf{X}^{(\ell)}\}_\ell \text{ are sparse.}$$

Choices for sparsity constraint?

- 1 **Classical sparsity patterns:** k -sparsity by column and/or by row
- 2 **Fixed-support constraint:** $\text{supp}(\mathbf{X}^{(\ell)}) \subseteq \mathbf{S}^{(\ell)}$ for $\ell = 1, \dots, J$.

A difficult problem

- Sparse coding is NP-hard.
[S. Foucart, H. Rauhut, **A mathematical introduction to compressive sensing**, ANHA, 2013]
- Fixed-support setting is NP-hard for $J = 2$ factors.
[Le et al., **Spurious valleys, NP-hardness, and tractability of sparse matrix fact. with fixed support**, SIMAX, 2022]
- Gradient-based methods lack guarantees.

How to factorize a matrix into sparse factors?

Problem formulation

$$\min_{\mathbf{X}^{(1)}, \dots, \mathbf{X}^{(J)}} \left\| \mathbf{Z} - \mathbf{X}^{(1)} \mathbf{X}^{(2)} \dots \mathbf{X}^{(J)} \right\|_F, \quad \text{such that } \{\mathbf{X}^{(\ell)}\}_\ell \text{ are sparse.}$$

Choices for sparsity constraint?

- 1 **Classical sparsity patterns:** k -sparsity by column and/or by row
- 2 **Fixed-support constraint:** $\text{supp}(\mathbf{X}^{(\ell)}) \subseteq \mathbf{S}^{(\ell)}$ for $\ell = 1, \dots, J$.

A difficult problem

- Sparse coding is NP-hard.
[S. Foucart, H. Rauhut, **A mathematical introduction to compressive sensing**, ANHA, 2013]
- Fixed-support setting is NP-hard for $J = 2$ factors.
[Le et al., **Spurious valleys, NP-hardness, and tractability of sparse matrix fact. with fixed support**, SIMAX, 2022]
- Gradient-based methods lack guarantees.

When is the problem well-posed? Uniqueness of solution? Stability?

→ Still an open question.

What makes the butterfly structure a good choice?

Case of square matrices of size $N = 2^J$.

What makes the butterfly structure a good choice?

Case of square matrices of size $N = 2^J$.

Definition (Butterfly structure)

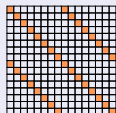
For each $\ell \in [J]$, $\text{supp}(\mathbf{X}^{(\ell)}) \subseteq \mathbf{S}_{\text{bf}}^{(\ell)}$

What makes the butterfly structure a good choice?

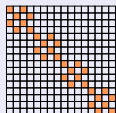
Case of square matrices of size $N = 2^J$.

Definition (Butterfly structure)

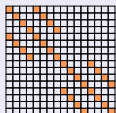
For each $\ell \in [J]$, $\text{supp}(\mathbf{X}^{(\ell)}) \subseteq \mathbf{S}_{\text{bf}}^{(\ell)}$, where $\mathbf{S}_{\text{bf}}^{(\ell)} := \mathbf{I}_{2^{\ell-1}} \otimes \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix} \otimes \mathbf{I}_{N/2^\ell}$.



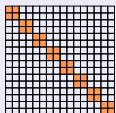
$\mathbf{S}_{\text{bf}}^{(1)}$



$\mathbf{S}_{\text{bf}}^{(2)}$



$\mathbf{S}_{\text{bf}}^{(3)}$



$\mathbf{S}_{\text{bf}}^{(4)}$

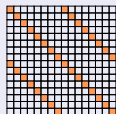
Example for
 $N = 16$, with 4
factors.

What makes the butterfly structure a good choice?

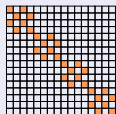
Case of square matrices of size $N = 2^J$.

Definition (Butterfly structure)

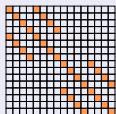
For each $\ell \in [J]$, $\text{supp}(\mathbf{X}^{(\ell)}) \subseteq \mathbf{S}_{\text{bf}}^{(\ell)}$, where $\mathbf{S}_{\text{bf}}^{(\ell)} := \mathbf{I}_{2^{\ell-1}} \otimes \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix} \otimes \mathbf{I}_{N/2^\ell}$.



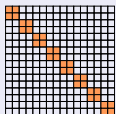
$\mathbf{S}_{\text{bf}}^{(1)}$



$\mathbf{S}_{\text{bf}}^{(2)}$



$\mathbf{S}_{\text{bf}}^{(3)}$



$\mathbf{S}_{\text{bf}}^{(4)}$

Example for
 $N = 16$, with 4
factors.

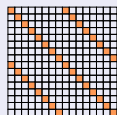
- 1 Enables fast $\mathcal{O}(N \log N)$ matrix-vector multiplication

What makes the butterfly structure a good choice?

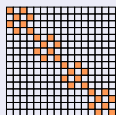
Case of square matrices of size $N = 2^J$.

Definition (Butterfly structure)

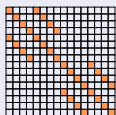
For each $\ell \in [J]$, $\text{supp}(\mathbf{X}^{(\ell)}) \subseteq \mathbf{S}_{\text{bf}}^{(\ell)}$, where $\mathbf{S}_{\text{bf}}^{(\ell)} := \mathbf{I}_{2^{\ell-1}} \otimes \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix} \otimes \mathbf{I}_{N/2^\ell}$.



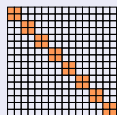
$\mathbf{S}_{\text{bf}}^{(1)}$



$\mathbf{S}_{\text{bf}}^{(2)}$



$\mathbf{S}_{\text{bf}}^{(3)}$

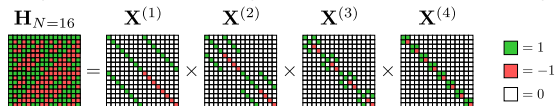


$\mathbf{S}_{\text{bf}}^{(4)}$

Example for $N = 16$, with 4 factors.

- 1 Enables fast $\mathcal{O}(N \log N)$ matrix-vector multiplication
- 2 Captures common fast transforms (Hadamard, DFT, DCT, ...)

[T. Dao et al., Kaleidoscope: An efficient, learnable representation for all structured linear maps, ICLR, 2020]

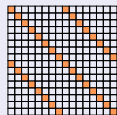


What makes the butterfly structure a good choice?

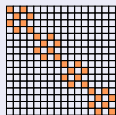
Case of square matrices of size $N = 2^J$.

Definition (Butterfly structure)

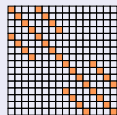
For each $\ell \in [J]$, $\text{supp}(\mathbf{X}^{(\ell)}) \subseteq \mathbf{S}_{\text{bf}}^{(\ell)}$, where $\mathbf{S}_{\text{bf}}^{(\ell)} := \mathbf{I}_{2^{\ell-1}} \otimes \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix} \otimes \mathbf{I}_{N/2^\ell}$.



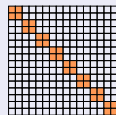
$\mathbf{S}_{\text{bf}}^{(1)}$



$\mathbf{S}_{\text{bf}}^{(2)}$



$\mathbf{S}_{\text{bf}}^{(3)}$

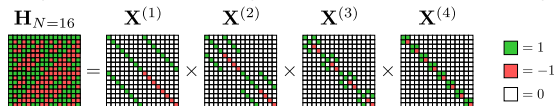


$\mathbf{S}_{\text{bf}}^{(4)}$

Example for $N = 16$, with 4 factors.

- 1 Enables fast $\mathcal{O}(N \log N)$ matrix-vector multiplication
- 2 Captures common fast transforms (Hadamard, DFT, DCT, ...)

[T. Dao et al., Kaleidoscope: An efficient, learnable representation for all structured linear maps, ICLR, 2020]



- 3 Makes the sparse matrix factorization problem well-posed

[L. Zheng et al., Efficient identification of butterfly sparse matrix factorizations, SIMODS, 2023]

Overview of this talk

Butterfly factorization problem

$$\min_{\mathbf{X}^{(1)}, \dots, \mathbf{X}^{(J)}} \left\| \mathbf{Z} - \mathbf{X}^{(1)} \mathbf{X}^{(2)} \dots \mathbf{X}^{(J)} \right\|_F, \quad \text{such that } \text{supp}(\mathbf{X}^{(\ell)}) \subseteq \mathbf{S}_{\text{bf}}^{(\ell)}.$$

Overview of this talk

Butterfly factorization problem

$$\min_{\mathbf{X}^{(1)}, \dots, \mathbf{X}^{(J)}} \left\| \mathbf{Z} - \mathbf{X}^{(1)} \mathbf{X}^{(2)} \dots \mathbf{X}^{(J)} \right\|_F, \quad \text{such that } \text{supp}(\mathbf{X}^{(\ell)}) \subseteq \mathbf{S}_{\text{bf}}^{(\ell)}.$$

- Gradient-descent method

[Le Magouarou et al., **Flexible multilayer sparse approximations of matrices and applications**, JSTSP, 2016]

[T. Dao et al., **Learning fast algorithms for linear transforms using butterfly factorizations**, ICML, 2019.]

- Hierarchical factorization (butterfly algorithms)

[Y. Li et al., **Butterfly factorization**, MMS, 2015]

Overview of this talk

Butterfly factorization problem

$$\min_{\mathbf{X}^{(1)}, \dots, \mathbf{X}^{(J)}} \left\| \mathbf{Z} - \mathbf{X}^{(1)} \mathbf{X}^{(2)} \dots \mathbf{X}^{(J)} \right\|_F, \quad \text{such that } \text{supp}(\mathbf{X}^{(\ell)}) \subseteq \mathbf{S}_{\text{bf}}^{(\ell)}.$$

- Gradient-descent method

[Le Magouarou et al., **Flexible multilayer sparse approximations of matrices and applications**, JSTSP, 2016]

[T. Dao et al., **Learning fast algorithms for linear transforms using butterfly factorizations**, ICML, 2019.]

- Hierarchical factorization (butterfly algorithms)

[Y. Li et al., **Butterfly factorization**, MMS, 2015]

Contributions

Overview of this talk

Butterfly factorization problem

$$\min_{\mathbf{X}^{(1)}, \dots, \mathbf{X}^{(J)}} \left\| \mathbf{Z} - \mathbf{X}^{(1)} \mathbf{X}^{(2)} \dots \mathbf{X}^{(J)} \right\|_F, \quad \text{such that } \text{supp}(\mathbf{X}^{(\ell)}) \subseteq \mathbf{S}_{\text{bf}}^{(\ell)}.$$

- Gradient-descent method

[Le Magouarou et al., **Flexible multilayer sparse approximations of matrices and applications**, JSTSP, 2016]
[T. Dao et al., **Learning fast algorithms for linear transforms using butterfly factorizations**, ICML, 2019.]

- Hierarchical factorization (butterfly algorithms)

[Y. Li et al., **Butterfly factorization**, MMS, 2015]

Contributions

- 1 We prove that the butterfly factorization is **essentially unique**.

$$\mathbf{X}^{(1)} \dots \mathbf{X}^{(J)} = \bar{\mathbf{X}}^{(1)} \dots \bar{\mathbf{X}}^{(J)} \implies (\mathbf{X}^{(\ell)})_{\ell=1}^J \sim (\bar{\mathbf{X}}^{(\ell)})_{\ell=1}^J$$

Overview of this talk

Butterfly factorization problem

$$\min_{\mathbf{X}^{(1)}, \dots, \mathbf{X}^{(J)}} \left\| \mathbf{Z} - \mathbf{X}^{(1)} \mathbf{X}^{(2)} \dots \mathbf{X}^{(J)} \right\|_F, \quad \text{such that } \text{supp}(\mathbf{X}^{(\ell)}) \subseteq \mathbf{S}_{\text{bf}}^{(\ell)}.$$

- Gradient-descent method

[Le Magouarou et al., **Flexible multilayer sparse approximations of matrices and applications**, JSTSP, 2016]
[T. Dao et al., **Learning fast algorithms for linear transforms using butterfly factorizations**, ICML, 2019.]

- Hierarchical factorization (butterfly algorithms)

[Y. Li et al., **Butterfly factorization**, MMS, 2015]

Contributions

- 1 We prove that the butterfly factorization is **essentially unique**.

$$\mathbf{X}^{(1)} \dots \mathbf{X}^{(J)} = \bar{\mathbf{X}}^{(1)} \dots \bar{\mathbf{X}}^{(J)} \implies (\mathbf{X}^{(\ell)})_{\ell=1}^J \sim (\bar{\mathbf{X}}^{(\ell)})_{\ell=1}^J$$

- 2 Factors are recovered by a **flexible** hierarchical factorization algorithm.

Overview of this talk

Butterfly factorization problem

$$\min_{\mathbf{X}^{(1)}, \dots, \mathbf{X}^{(J)}} \left\| \mathbf{Z} - \mathbf{X}^{(1)} \mathbf{X}^{(2)} \dots \mathbf{X}^{(J)} \right\|_F, \quad \text{such that } \text{supp}(\mathbf{X}^{(\ell)}) \subseteq \mathbf{S}_{\text{bf}}^{(\ell)}.$$

- Gradient-descent method

[Le Magouarou et al., **Flexible multilayer sparse approximations of matrices and applications**, JSTSP, 2016]
[T. Dao et al., **Learning fast algorithms for linear transforms using butterfly factorizations**, ICML, 2019.]

- Hierarchical factorization (butterfly algorithms)

[Y. Li et al., **Butterfly factorization**, MMS, 2015]

Contributions

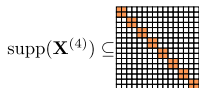
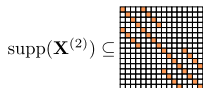
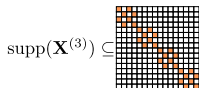
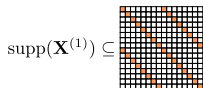
- 1 We prove that the butterfly factorization is **essentially unique**.

$$\mathbf{X}^{(1)} \dots \mathbf{X}^{(J)} = \bar{\mathbf{X}}^{(1)} \dots \bar{\mathbf{X}}^{(J)} \implies (\mathbf{X}^{(\ell)})_{\ell=1}^J \sim (\bar{\mathbf{X}}^{(\ell)})_{\ell=1}^J$$

- 2 Factors are recovered by a **flexible** hierarchical factorization algorithm.
- 3 The algo. is **numerically faster, more accurate** than gradient-descent.

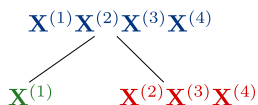
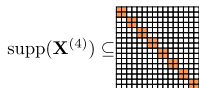
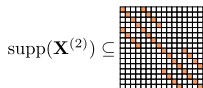
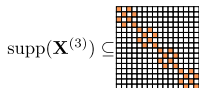
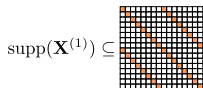
Hierarchical factorization algorithm

Let $\mathbf{Z} := \mathbf{X}^{(1)}\mathbf{X}^{(2)}\mathbf{X}^{(3)}\mathbf{X}^{(4)}$ such that:



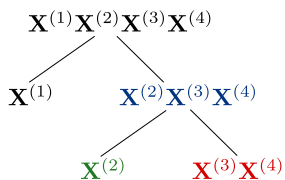
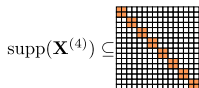
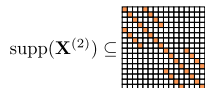
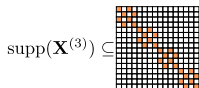
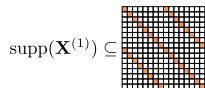
Hierarchical factorization algorithm

Let $\mathbf{Z} := \mathbf{X}^{(1)}\mathbf{X}^{(2)}\mathbf{X}^{(3)}\mathbf{X}^{(4)}$ such that:



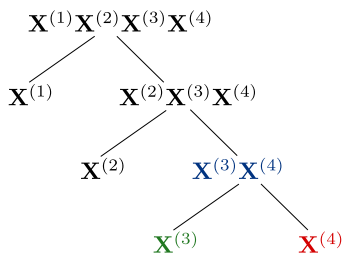
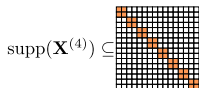
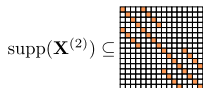
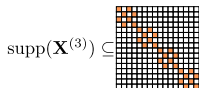
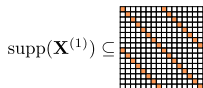
Hierarchical factorization algorithm

Let $\mathbf{Z} := \mathbf{X}^{(1)}\mathbf{X}^{(2)}\mathbf{X}^{(3)}\mathbf{X}^{(4)}$ such that:



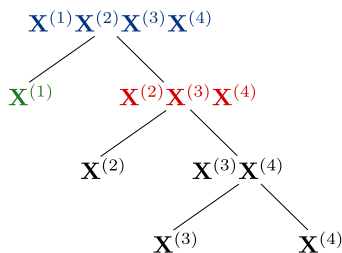
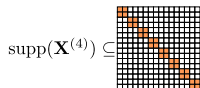
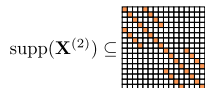
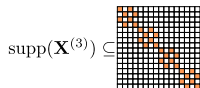
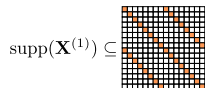
Hierarchical factorization algorithm

Let $\mathbf{Z} := \mathbf{X}^{(1)}\mathbf{X}^{(2)}\mathbf{X}^{(3)}\mathbf{X}^{(4)}$ such that:



Hierarchical factorization algorithm

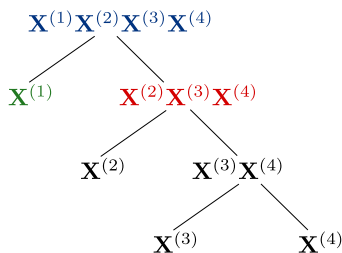
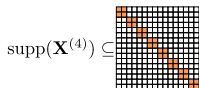
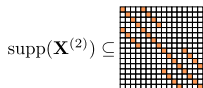
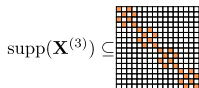
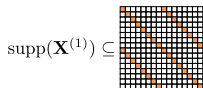
Let $\mathbf{Z} := \mathbf{X}^{(1)}\mathbf{X}^{(2)}\mathbf{X}^{(3)}\mathbf{X}^{(4)}$ such that:



How to recover the partial products?

Hierarchical factorization algorithm

Let $\mathbf{Z} := \mathbf{X}^{(1)}\mathbf{X}^{(2)}\mathbf{X}^{(3)}\mathbf{X}^{(4)}$ such that:



How to recover the partial products? \rightarrow use their known supports

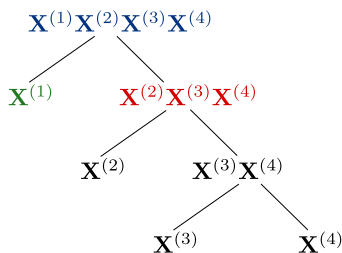
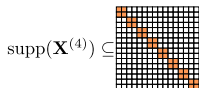
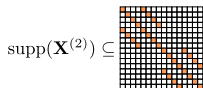
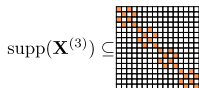
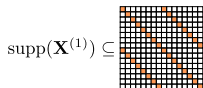
Lemma (Supports of the partial products)

$$\text{supp}(\mathbf{X}^{(1)}) \subseteq \text{img} = \mathbf{S}_{\text{bf}}^{(1)}$$

$$\text{supp}(\mathbf{X}^{(2)}\mathbf{X}^{(3)}\mathbf{X}^{(4)}) \subseteq \text{img} = \mathbf{S}_{\text{bf}}^{(2)}\mathbf{S}_{\text{bf}}^{(3)}\mathbf{S}_{\text{bf}}^{(4)}$$

Hierarchical factorization algorithm

Let $\mathbf{Z} := \mathbf{X}^{(1)}\mathbf{X}^{(2)}\mathbf{X}^{(3)}\mathbf{X}^{(4)}$ such that:



How to recover the partial products? \rightarrow use their known supports

Lemma (Supports of the partial products)

$$\text{supp}(\mathbf{X}^{(1)}) \subseteq \text{img}(\mathbf{S}_{\text{bf}}^{(1)}) = \mathbf{S}_{\text{bf}}^{(1)}$$

$$\text{supp}(\mathbf{X}^{(2)}\mathbf{X}^{(3)}\mathbf{X}^{(4)}) \subseteq \text{img}(\mathbf{S}_{\text{bf}}^{(2)}\mathbf{S}_{\text{bf}}^{(3)}\mathbf{S}_{\text{bf}}^{(4)}) = \mathbf{S}_{\text{bf}}^{(2)}\mathbf{S}_{\text{bf}}^{(3)}\mathbf{S}_{\text{bf}}^{(4)}$$

Two-layer fixed-support problem:

$$\min_{\mathbf{A}, \mathbf{B}} \|\mathbf{Z} - \mathbf{A}\mathbf{B}\|_F, \text{ s.t. } \text{supp}(\mathbf{A}) \subseteq \mathbf{S}_{\text{bf}}^{(1)}, \text{supp}(\mathbf{B}) \subseteq \mathbf{S}_{\text{bf}}^{(2)}\mathbf{S}_{\text{bf}}^{(3)}\mathbf{S}_{\text{bf}}^{(4)} \quad (\star)$$

Two-layer fixed-support sparse matrix factorization

$$\min_{\mathbf{A}, \mathbf{B}} \|\mathbf{Z} - \mathbf{A}\mathbf{B}\|_F, \text{ s.t. } \text{supp}(\mathbf{A}) \subseteq \mathbf{S}_{\text{bf}}^{(1)}, \text{supp}(\mathbf{B}) \subseteq \mathbf{S}_{\text{bf}}^{(2)}\mathbf{S}_{\text{bf}}^{(3)}\mathbf{S}_{\text{bf}}^{(4)} \quad (\star)$$

Two-layer fixed-support sparse matrix factorization

$$\min_{\mathbf{A}, \mathbf{B}} \|\mathbf{Z} - \mathbf{A}\mathbf{B}\|_F, \text{ s.t. } \text{supp}(\mathbf{A}) \subseteq \mathbf{S}_{\text{bf}}^{(1)}, \text{supp}(\mathbf{B}) \subseteq \mathbf{S}_{\text{bf}}^{(2)}\mathbf{S}_{\text{bf}}^{(3)}\mathbf{S}_{\text{bf}}^{(4)} \quad (\star)$$

Fact: $\mathbf{A}\mathbf{B} = \sum_{i=1}^N \mathbf{A}_{\bullet, i} \mathbf{B}_{i, \bullet}$.

Two-layer fixed-support sparse matrix factorization

$$\min_{\mathbf{A}, \mathbf{B}} \|\mathbf{Z} - \mathbf{A}\mathbf{B}\|_F, \text{ s.t. } \text{supp}(\mathbf{A}) \subseteq \mathbf{S}_{\text{bf}}^{(1)}, \text{supp}(\mathbf{B}) \subseteq \mathbf{S}_{\text{bf}}^{(2)}\mathbf{S}_{\text{bf}}^{(3)}\mathbf{S}_{\text{bf}}^{(4)} \quad (\star)$$

Fact: $\mathbf{A}\mathbf{B} = \sum_{i=1}^N \mathbf{A}_{\bullet,i} \mathbf{B}_{i,\bullet}$.

Constraint on the pair of factors

$$\text{supp}(\mathbf{A}) \subseteq \begin{array}{c} \text{[Grid with green diagonal bands]} \\ = \mathbf{S}_{\text{bf}}^{(1)} \end{array}$$

$$\text{supp}(\mathbf{B}) \subseteq \begin{array}{c} \text{[Grid with red blocks]} \\ = \mathbf{S}_{\text{bf}}^{(2)}\mathbf{S}_{\text{bf}}^{(3)}\mathbf{S}_{\text{bf}}^{(4)} \end{array}$$

Two-layer fixed-support sparse matrix factorization

$$\min_{\mathbf{A}, \mathbf{B}} \|\mathbf{Z} - \mathbf{A}\mathbf{B}\|_F, \text{ s.t. } \text{supp}(\mathbf{A}) \subseteq \mathbf{S}_{\text{bf}}^{(1)}, \text{supp}(\mathbf{B}) \subseteq \mathbf{S}_{\text{bf}}^{(2)} \mathbf{S}_{\text{bf}}^{(3)} \mathbf{S}_{\text{bf}}^{(4)} \quad (\star)$$

Fact: $\mathbf{A}\mathbf{B} = \sum_{i=1}^N \mathbf{A}_{\bullet,i} \mathbf{B}_{i,\bullet}$.

Constraint on the pair of factors

$$\text{supp}(\mathbf{A}) \subseteq \begin{array}{c} \text{[Grid with green diagonal lines]} \\ = \mathbf{S}_{\text{bf}}^{(1)} \end{array}$$

$$\text{supp}(\mathbf{B}) \subseteq \begin{array}{c} \text{[Grid with red blocks]} \\ = \mathbf{S}_{\text{bf}}^{(2)} \mathbf{S}_{\text{bf}}^{(3)} \mathbf{S}_{\text{bf}}^{(4)} \end{array}$$

Constraint on the rank-one matrices

$$\text{supp}(\mathbf{A}_{\bullet,1} \mathbf{B}_{1,\bullet}) \subseteq \begin{array}{c} \text{[Grid with blue horizontal lines]} \\ = \mathcal{S}_1 \end{array}$$

$$\text{supp}(\mathbf{A}_{\bullet,2} \mathbf{B}_{2,\bullet}) \subseteq \begin{array}{c} \text{[Grid with yellow horizontal lines]} \\ = \mathcal{S}_2 \end{array}$$

⋮

$$\text{supp}(\mathbf{A}_{\bullet,N} \mathbf{B}_{N,\bullet}) \subseteq \begin{array}{c} \text{[Grid with purple horizontal lines]} \\ = \mathcal{S}_N \end{array}$$

Two-layer fixed-support sparse matrix factorization

$$\min_{\mathbf{A}, \mathbf{B}} \|\mathbf{Z} - \mathbf{A}\mathbf{B}\|_F, \text{ s.t. } \text{supp}(\mathbf{A}) \subseteq \mathbf{S}_{\text{bf}}^{(1)}, \text{supp}(\mathbf{B}) \subseteq \mathbf{S}_{\text{bf}}^{(2)}\mathbf{S}_{\text{bf}}^{(3)}\mathbf{S}_{\text{bf}}^{(4)} \quad (\star)$$

Constraint on the rank-one matrices

$$\begin{aligned} \text{supp}(\mathbf{A}_{\bullet,1}\mathbf{B}_{1,\bullet}) &\subseteq \begin{array}{c} \text{[grid with blue and red highlights]} \end{array} = \mathcal{S}_1 && \dots \\ \text{supp}(\mathbf{A}_{\bullet,2}\mathbf{B}_{2,\bullet}) &\subseteq \begin{array}{c} \text{[grid with yellow and orange highlights]} \end{array} = \mathcal{S}_2 && \text{supp}(\mathbf{A}_{\bullet,N}\mathbf{B}_{N,\bullet}) \subseteq \begin{array}{c} \text{[grid with purple and blue highlights]} \end{array} = \mathcal{S}_N \end{aligned}$$

Theorem ([Le et al. 2022; Zheng et al. 2023])

*The rank-one matrices have **pairwise disjoint supports**.*

Two-layer fixed-support sparse matrix factorization

$$\min_{\mathbf{A}, \mathbf{B}} \|\mathbf{Z} - \mathbf{A}\mathbf{B}\|_F, \text{ s.t. } \text{supp}(\mathbf{A}) \subseteq \mathbf{S}_{\text{bf}}^{(1)}, \text{supp}(\mathbf{B}) \subseteq \mathbf{S}_{\text{bf}}^{(2)}\mathbf{S}_{\text{bf}}^{(3)}\mathbf{S}_{\text{bf}}^{(4)} \quad (\star)$$

Constraint on the rank-one matrices

$$\begin{aligned} \text{supp}(\mathbf{A}_{\bullet,1}\mathbf{B}_{1,\bullet}) &\subseteq \begin{array}{c} \text{[grid with blue and red highlights]} \\ \text{[grid with blue and red highlights]} \\ \text{[grid with blue and red highlights]} \end{array} = \mathcal{S}_1 && \dots \\ \text{supp}(\mathbf{A}_{\bullet,2}\mathbf{B}_{2,\bullet}) &\subseteq \begin{array}{c} \text{[grid with yellow and red highlights]} \\ \text{[grid with yellow and red highlights]} \\ \text{[grid with yellow and red highlights]} \end{array} = \mathcal{S}_2 && \text{supp}(\mathbf{A}_{\bullet,N}\mathbf{B}_{N,\bullet}) \subseteq \begin{array}{c} \text{[grid with purple and blue highlights]} \\ \text{[grid with purple and blue highlights]} \\ \text{[grid with purple and blue highlights]} \end{array} = \mathcal{S}_N \end{aligned}$$

Theorem ([Le et al. 2022; Zheng et al. 2023])

The rank-one matrices have **pairwise disjoint supports**. Consequently:

- 1 there exists a *polynomial* algorithm to find an *optimal* solution to (\star)

Two-layer fixed-support sparse matrix factorization

$$\min_{\mathbf{A}, \mathbf{B}} \|\mathbf{Z} - \mathbf{A}\mathbf{B}\|_F, \text{ s.t. } \text{supp}(\mathbf{A}) \subseteq \mathbf{S}_{\text{bf}}^{(1)}, \text{supp}(\mathbf{B}) \subseteq \mathbf{S}_{\text{bf}}^{(2)} \mathbf{S}_{\text{bf}}^{(3)} \mathbf{S}_{\text{bf}}^{(4)} \quad (\star)$$

Constraint on the rank-one matrices

$$\begin{aligned} \text{supp}(\mathbf{A}_{\bullet,1} \mathbf{B}_{1,\bullet}) &\subseteq \begin{array}{|c|} \hline \color{red}{\bullet} \color{blue}{\bullet} \\ \hline \end{array} = \mathcal{S}_1 & \dots \\ \text{supp}(\mathbf{A}_{\bullet,2} \mathbf{B}_{2,\bullet}) &\subseteq \begin{array}{|c|} \hline \color{yellow}{\bullet} \color{orange}{\bullet} \\ \hline \end{array} = \mathcal{S}_2 & \text{supp}(\mathbf{A}_{\bullet,N} \mathbf{B}_{N,\bullet}) \subseteq \begin{array}{|c|} \hline \color{purple}{\bullet} \color{green}{\bullet} \\ \hline \end{array} = \mathcal{S}_N \end{aligned}$$

Theorem ([Le et al. 2022; Zheng et al. 2023])

The rank-one matrices have **pairwise disjoint supports**. Consequently:

- 1 there exists a *polynomial* algorithm to find an *optimal* solution to (\star)
- 2 the solution is essentially *unique* in the noiseless setting.

Two-layer fixed-support sparse matrix factorization

$$\min_{\mathbf{A}, \mathbf{B}} \|\mathbf{Z} - \mathbf{A}\mathbf{B}\|_F, \text{ s.t. } \text{supp}(\mathbf{A}) \subseteq \mathbf{S}_{\text{bf}}^{(1)}, \text{supp}(\mathbf{B}) \subseteq \mathbf{S}_{\text{bf}}^{(2)} \mathbf{S}_{\text{bf}}^{(3)} \mathbf{S}_{\text{bf}}^{(4)} \quad (\star)$$

Constraint on the rank-one matrices

$$\begin{aligned} \text{supp}(\mathbf{A}_{\bullet,1} \mathbf{B}_{1,\bullet}) &\subseteq \begin{array}{|c|} \hline \color{red}{\bullet} \color{blue}{\bullet} \color{green}{\bullet} \\ \hline \end{array} = \mathcal{S}_1 & \dots \\ \text{supp}(\mathbf{A}_{\bullet,2} \mathbf{B}_{2,\bullet}) &\subseteq \begin{array}{|c|} \hline \color{yellow}{\bullet} \color{orange}{\bullet} \\ \hline \end{array} = \mathcal{S}_2 & \text{supp}(\mathbf{A}_{\bullet,N} \mathbf{B}_{N,\bullet}) \subseteq \begin{array}{|c|} \hline \color{purple}{\bullet} \color{blue}{\bullet} \\ \hline \end{array} = \mathcal{S}_N \end{aligned}$$

Theorem ([Le et al. 2022; Zheng et al. 2023])

The rank-one matrices have **pairwise disjoint supports**. Consequently:


- 1 there exists a **polynomial** algorithm to find an **optimal** solution to (\star)
- 2 the solution is essentially **unique** in the noiseless setting.


Algorithm:


- 1 Extract the submatrices $\mathbf{Z}_{|\mathcal{S}_i}$, $i = 1, \dots, N$
- 2 Perform best **rank-one** approximation for each submatrix


Hierarchical factorization algorithm

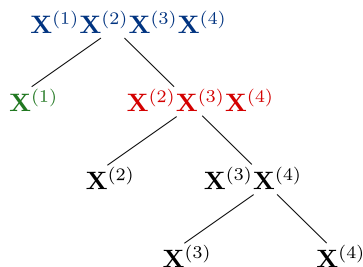
Let $\mathbf{Z} := \mathbf{X}^{(1)}\mathbf{X}^{(2)}\mathbf{X}^{(3)}\mathbf{X}^{(4)}$ such that:

$$\text{supp}(\mathbf{X}^{(1)}) \subseteq \text{img}(\text{grid})$$


$$\text{supp}(\mathbf{X}^{(3)}) \subseteq \text{img}(\text{grid})$$



$$\text{supp}(\mathbf{X}^{(2)}) \subseteq \text{img}(\text{grid})$$



$$\text{supp}(\mathbf{X}^{(4)}) \subseteq \text{img}(\text{grid})$$




The two-layer procedure is repeated **recursively**.

Lemma (Support of the partial products)

$$\text{supp}(\mathbf{X}^{(1)}) \subseteq \text{img}(\text{grid}) = \mathbf{S}_{\text{bf}}^{(1)}$$


$$\text{supp}(\mathbf{X}^{(2)}\mathbf{X}^{(3)}\mathbf{X}^{(4)}) \subseteq \text{img}(\text{grid}) = \mathbf{S}_{\text{bf}}^{(2)}\mathbf{S}_{\text{bf}}^{(3)}\mathbf{S}_{\text{bf}}^{(4)}$$


Corresponding rank-one supports are pairwise disjoint.

Hierarchical factorization algorithm

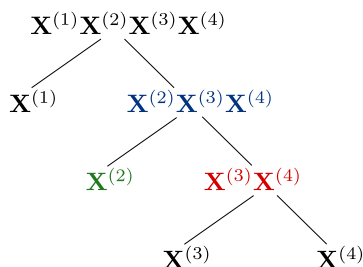
Let $\mathbf{Z} := \mathbf{X}^{(1)}\mathbf{X}^{(2)}\mathbf{X}^{(3)}\mathbf{X}^{(4)}$ such that:

$$\text{supp}(\mathbf{X}^{(1)}) \subseteq \text{img}(\text{grid with orange diagonal})$$

$$\text{supp}(\mathbf{X}^{(3)}) \subseteq \text{img}(\text{grid with orange diagonal})$$

$$\text{supp}(\mathbf{X}^{(2)}) \subseteq \text{img}(\text{grid with orange diagonal})$$

$$\text{supp}(\mathbf{X}^{(4)}) \subseteq \text{img}(\text{grid with orange diagonal})$$



The two-layer procedure is repeated **recursively**.

Lemma (Support of the partial products)

$$\text{supp}(\mathbf{X}^{(2)}) \subseteq \text{img}(\text{grid with green diagonal}) = \mathbf{S}_{\text{bf}}^{(2)}$$

$$\text{supp}(\mathbf{X}^{(3)}\mathbf{X}^{(4)}) \subseteq \text{img}(\text{grid with red blocks}) = \mathbf{S}_{\text{bf}}^{(3)}\mathbf{S}_{\text{bf}}^{(4)}$$

Corresponding rank-one supports are pairwise disjoint.

Hierarchical factorization algorithm

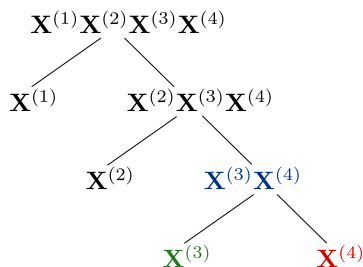
Let $\mathbf{Z} := \mathbf{X}^{(1)}\mathbf{X}^{(2)}\mathbf{X}^{(3)}\mathbf{X}^{(4)}$ such that:

$$\text{supp}(\mathbf{X}^{(1)}) \subseteq \text{img}(\text{grid})$$

$$\text{supp}(\mathbf{X}^{(3)}) \subseteq \text{img}(\text{grid})$$

$$\text{supp}(\mathbf{X}^{(2)}) \subseteq \text{img}(\text{grid})$$

$$\text{supp}(\mathbf{X}^{(4)}) \subseteq \text{img}(\text{grid})$$



The two-layer procedure is repeated **recursively**.

Lemma (Support of the partial products)

$$\text{supp}(\mathbf{X}^{(3)}) \subseteq \text{img}(\text{grid}) = \mathbf{S}_{\text{bf}}^{(3)}$$

$$\text{supp}(\mathbf{X}^{(4)}) \subseteq \text{img}(\text{grid}) = \mathbf{S}_{\text{bf}}^{(4)}$$

Corresponding rank-one supports are pairwise disjoint.

Hierarchical factorization algorithm

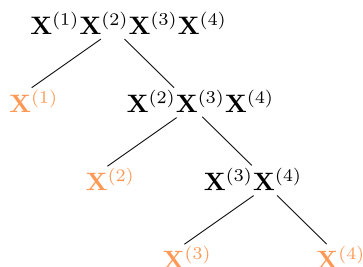
Let $\mathbf{Z} := \mathbf{X}^{(1)}\mathbf{X}^{(2)}\mathbf{X}^{(3)}\mathbf{X}^{(4)}$ such that:

$$\text{supp}(\mathbf{X}^{(1)}) \subseteq \text{img}(\text{grid})$$

$$\text{supp}(\mathbf{X}^{(3)}) \subseteq \text{img}(\text{grid})$$

$$\text{supp}(\mathbf{X}^{(2)}) \subseteq \text{img}(\text{grid})$$

$$\text{supp}(\mathbf{X}^{(4)}) \subseteq \text{img}(\text{grid})$$



The two-layer procedure is repeated **recursively**.

Lemma (Support of the partial products)

$$\text{supp}(\mathbf{X}^{(3)}) \subseteq \text{img}(\text{grid}) = \mathbf{S}_{\text{bf}}^{(3)}$$

$$\text{supp}(\mathbf{X}^{(4)}) \subseteq \text{img}(\text{grid}) = \mathbf{S}_{\text{bf}}^{(4)}$$

Corresponding rank-one supports are pairwise disjoint.

$\{\mathbf{X}^{(\ell)}\}_{\ell=1}^4$ are recovered from \mathbf{Z} , up to scaling ambiguities.

Uniqueness of butterfly factorization

Theorem ([Zheng et al. 2023])

Except for trivial degeneracies, *the butterfly factorization $\mathbf{Z} := \mathbf{X}^{(1)} \dots \mathbf{X}^{(J)}$ is essentially unique*, up to unavoidable scaling ambiguities:

$$\begin{cases} \bar{\mathbf{X}}^{(1)} \dots \bar{\mathbf{X}}^{(J)} = \mathbf{Z} \\ \forall \ell \in [J], \text{supp}(\bar{\mathbf{X}}^{(\ell)}) \subseteq \mathbf{s}_{\text{bf}}^{(\ell)} \end{cases} \implies (\bar{\mathbf{X}}^{(\ell)})_{\ell=1}^J \sim (\mathbf{X}^{(\ell)})_{\ell=1}^J$$

The unique factors are *recovered* from the hierarchical algorithm.

Uniqueness of butterfly factorization

Theorem ([Zheng et al. 2023])

Except for trivial degeneracies, *the butterfly factorization $\mathbf{Z} := \mathbf{X}^{(1)} \dots \mathbf{X}^{(J)}$ is essentially unique*, up to unavoidable scaling ambiguities:

$$\begin{cases} \bar{\mathbf{X}}^{(1)} \dots \bar{\mathbf{X}}^{(J)} = \mathbf{Z} \\ \forall \ell \in [J], \text{supp}(\bar{\mathbf{X}}^{(\ell)}) \subseteq \mathbf{s}_{\text{bf}}^{(\ell)} \end{cases} \implies (\bar{\mathbf{X}}^{(\ell)})_{\ell=1}^J \sim (\mathbf{X}^{(\ell)})_{\ell=1}^J$$

The unique factors are *recovered* from the hierarchical algorithm.

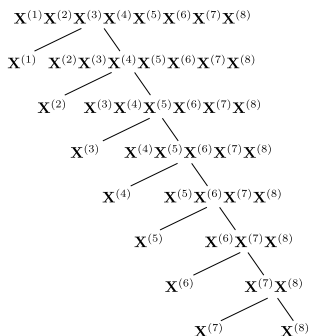
Proof: at level ℓ , the intermediate matrix to factorize is

$$\mathbf{M} := \underbrace{(\mathbf{D}^{-1} \mathbf{X}^{(\ell)})}_{\mathbf{A}} \underbrace{(\mathbf{X}^{(\ell+1)} \dots \mathbf{X}^{(J)} \tilde{\mathbf{D}})}_{\mathbf{B}}.$$

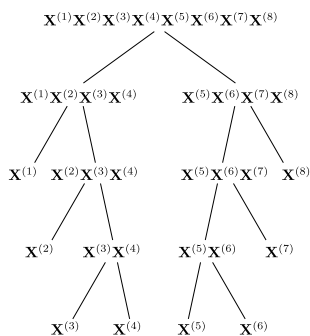
The algorithm recovers (\mathbf{A}, \mathbf{B}) because of optimality & uniqueness in (\star) .

Flexible choice in the hierarchical order

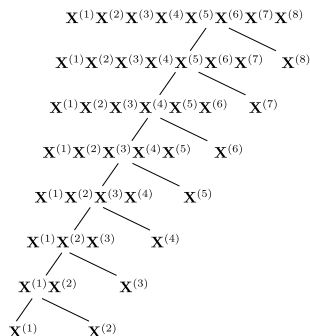
The algorithm works for **any factor-bracketing binary tree**.



Column-wise factorization



Hybrid factorization



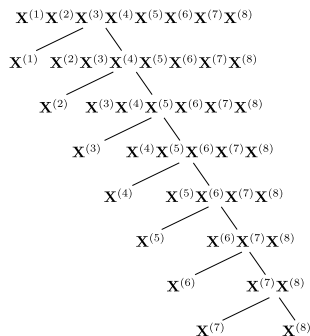
Row-wise factorization

This extends existing work that consider only 3 trees.

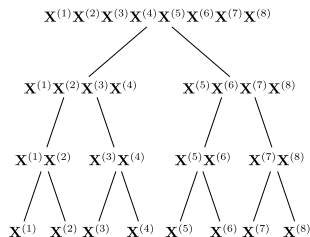
[Y. Liu et al., **Butterfly factorization via randomized matrix-vector multiplications**, SISC, 2021]

Flexible choice in the hierarchical order

The algorithm works for **any factor-bracketing binary tree**.



Unbalanced tree



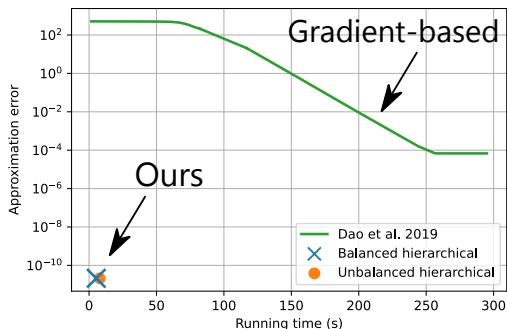
Balanced tree (new)

This extends existing work that consider only 3 trees.

[Y. Liu et al., **Butterfly factorization via randomized matrix-vector multiplications**, SISC, 2021]

Faster and more accurate in the noiseless setting

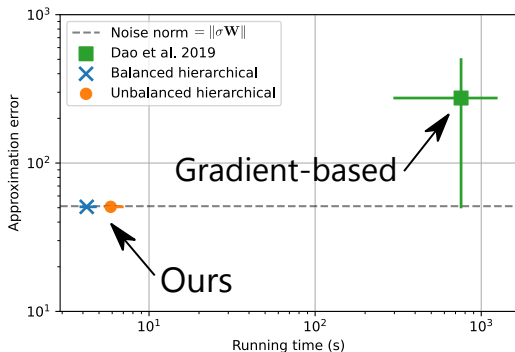
Approximate $\mathbf{Z} := \mathbf{DFT}_{512}$ by a product of $J = 9$ butterfly factors:



The theoretical complexity of the algorithm is $\mathcal{O}(N^2)$.

Also more robust in the noisy setting

Approximate $\mathbf{Z} := \mathbf{DFT}_{512} + \sigma\mathbf{W}$ by a product of $J = 9$ butterfly factors:



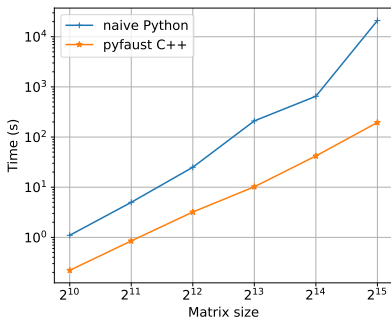
FA μ ST Toolbox: faust.inria.fr

Efficient implem. of fast transforms and algorithms for sparse matrix fact.

- Python & MATLAB wrappers (C++ core, GPU compatible)
- PYPI install: `pip install pyfaust`

Ex: butterfly factorization

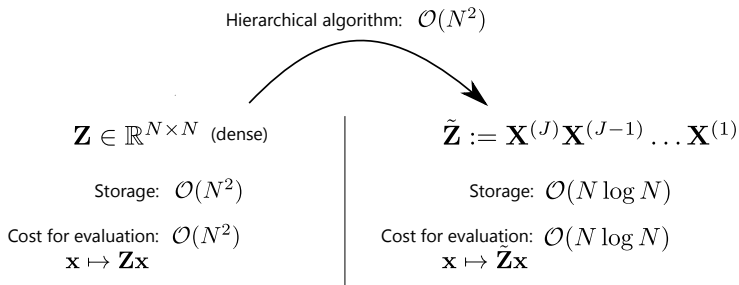
```
1 from pyfaust.fact import butterfly
2 from pyfaust import Faust, wht
3
4 H = wht(8).toarray()
5 F = butterfly(H, type='bbtree')
6 (F-H).norm() / Faust(H).norm()
7 # Output: 1.2560739454502295e-15
```



Factorization of the Hadamard matrix with a balanced tree.

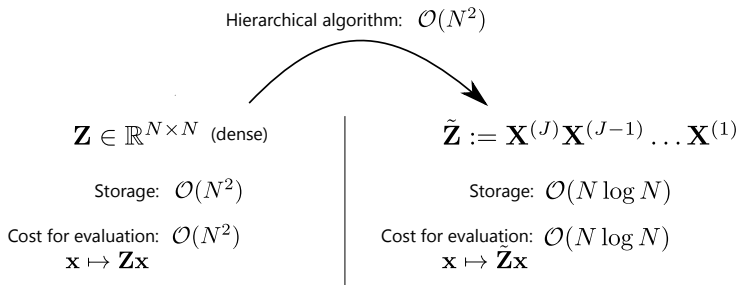
Conclusion and perspectives

- 1 The butterfly structure captures many common fast transforms.
- 2 We proved the **essential uniqueness** of the butterfly factorization.
- 3 Butterfly factors are recovered by a **flexible hierarchical algorithm**.



Conclusion and perspectives

- 1 The butterfly structure captures many common fast transforms.
- 2 We proved the **essential uniqueness** of the butterfly factorization.
- 3 Butterfly factors are recovered by a **flexible hierarchical algorithm**.



On going work

- Approximation error of the hierarchical algorithm
- Taking into account row and column permutations
- Efficient training of neural networks with butterfly structure

Thank you for your attention!

To know more:



Q.-T. Le, L. Zheng, E. Riccietti, and R. Gribonval
Fast learning of fast transforms, with guarantees
In *ICASSP*, 2022.



Q.-T. Le, E. Riccietti, and R. Gribonval
Spurious valleys, NP-hardness, and tractability of sparse matrix factorization with fixed support
In *SIAM Journal on Matrix Analysis and Applications*, 2022.



L. Zheng, E. Riccietti, and R. Gribonval
Efficient identification of butterfly sparse matrix factorizations
In *SIAM Journal on Mathematics of Data Science*, 2023.